

Manufacturer	FOCQUET
Reference	CO 2016 0433
Type	MF 315LB-08 MF 355MB-08
Customer	TES INDUSTRIAL SYSTEMS B.V.
Reference	P0446.10/16021503



## Declaration of Compliance

Buyer : **TES INDUSTRIAL SYSTEMS B.V.**  
Mechanisatieweg 2  
4906 AE Oosterhout, Netherlands

Order no. : **P0446.10/16021503**

Scope of delivery :

<b>Nº</b>	<b>Quantity</b>	<b>Description</b>	<b>Type</b>
01	1	AC Squirrel Cage Induction Motor	MF 315LB-08
02	1	AC Squirrel Cage Induction Motor	MF 355MB-08

We certify that the listed products have been manufactured, examined and delivered according to the technical specifications of the order.

GEMBLOUX, 20<sup>th</sup> April 2016

\_\_\_\_\_  
Person in charge

The electrical apparatus:

Three-phase asynchronous motor with squirrel-cage rotor  
& Three-phase asynchronous motor with slip ring rotor

Of the series **MA / MF / MB**

Followed by the motor type, are in conformity with the instructions of the following EU directives:

**2006/95/EG**  
**2004/108/EG**

The conformity with the instructions of these directives is proved by the observation of the following standards:

**EN 61000-6-1, EN 61000-6-2, EN 61000-6-3, EN 61000-6-4**  
**EN 55014-1, EN 55014-2**  
**EN 61000-3-2, EN 61000-3-3**  
**EN 60034-1, EN 60034-2-1, EN 60034-5. EN 60034-6, EN 60034-9, EN 60034-30**  
**IEC 60038**  
**EN 60204-1**

The specified product is exclusively intended for fitting into another machine. Start of operation is permitted until conformity of the end product with the directive **2006/42/EC** is established.

Gembloux, 01<sup>st</sup> January 2015

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**Bruno Focquet**  
*Managing Director*

This certificate attests the conformity with the named Directives; however, it is not a promise of properties in the meaning of product liability.

*In case of electronic communication, the signature does not appear.*

<b>Data</b>		
<b>Rotor</b>		Squirrel Cage Rotor
<b>Type</b>		<b>MF 315LB-08</b>
<b>Serial Number</b>		20160433-01
<b>Design</b>		IEC 34-1 / EN60034-1
<b>Duty</b>		S1
<b>Phase</b>		3
<b>Power</b>	kW	110
<b>Voltage</b>	V	400
<b>Tolerance</b>	%	+/- 10
<b>Frequency</b>	Hz	50
<b>Tolerance</b>	%	+/- 2
<b>Connection</b>		Δ
<b>Poles</b>		8
<b>Speed</b>	rpm	735
<b>Direction of Rotation</b>		Both
<b>Current</b>	A	206
<b>Efficiency</b>	%	94
<b>Power Factor</b>		0,82
<b>Torque</b>	Nm	1.429
<b>Start Up</b>		DOL / VFD
<b>I<sub>A</sub>/I<sub>N</sub></b>	%	640
<b>M<sub>A</sub>/M<sub>N</sub></b>	%	180
<b>M<sub>K</sub>/M<sub>N</sub></b>	%	200
<b>Mounting</b>		IM B3
<b>Frame Size</b>		315 L
<b>Housing material</b>		Cast Iron
<b>Protection</b>		IP 55
<b>Cooling</b>		IC 411
<b>Balancing</b>		Half Key
<b>Insulation class</b>		F
<b>Temperature Rise</b>		B
<b>Weight</b>	kg	~1.150

<b>Bearings &amp; Lubrication</b>		
<b>Bearing Type</b>	Antifriction Bearing	
<b>Cooling</b>	Self Cooled	
<b>Type</b>	Drive End	6319.C3
	Non Drive End	6319.C3 – Insulated
<b>Lubrication interval</b>	h	6.100
<b>Volume of Grease</b>	g	45
<b>Lubricant</b>	Caltex SRI-2	
<b>Painting</b>		
<b>System</b>	Moderate	
<b>Colour</b>	RAL 7030	
<b>Vibration</b>		
<b>Vibration</b>	mm/s	< 2,8
<b>Starting</b>		
<b>Starts</b>	Cold	3
	Warm	2
	Per Year	1.000
<b>Ambiance</b>		
<b>Ambient temperature</b>	°C	- 20 ... + 40
<b>Altitude</b>	m above sea level	≤ 1.270
<b>Humidity</b>	%	< 95
<b>Installation</b>	Outdoor / Indoor	
<b>Accessories</b>		
Regreasing device		
KTY 84/130 Sensor		
Metal Fan		
Encoder Hübner HOG 10 DN 1024 I LR 16H7 + ESL90		

Date (d/m/y): 19/04/2016

Customer: TES

Motor: MF 315LB-08

Serial No: 20160433-01

### Test Report

#### Name-Plate Data

Duty	S1	$\Delta$		
f [Hz]	50	U <sub>N</sub> [V]	400	cos $\phi$ 0,82
n <sub>N</sub> [min-1]	735	I <sub>N</sub> [A]	206	P <sub>N</sub> [kW] 110
IP	55	IS.Class	F	Net B3 [kg] 1118

Drive-end Bearing

319

Non drive-end Bearing

6319

Phase-Resistance at 20°C

[ $\Omega$ ] 0,0257

[ $\Omega$ ] 0,0258

[ $\Omega$ ] 0,0257

#### TEMPERATURE-RISE TEST

Conn.	U [V]	f [Hz]	I <sub>N</sub> ass [A]	P <sub>N</sub> res [kW]	Lasting [h]	Terminals	Winding $\theta$		Wind. Res. [ $\Omega$ ]	Amb. $\theta$ [°C]	Frame $\theta$		Wind. Res. [ $\Omega$ ]	Temperature Rise $\Delta\theta$ [K]
							Initial [°C]	Final [°C]			Initial [°C]	Final [°C]		
$\Delta$	400	50	206	110	4		20	0,026	22	62	0,033		69,2	

#### LOAD TEST

Conn.	Load	U [V]	f [Hz]	n [min-1]	S %	I [A]	input [kW]	T <sub>N</sub> [Nm]	out [kW]	$\eta$ %	cos $\phi$	Notes
$\Delta$	25 %	400	50	748	0,267	80	31,55	351,1	27,5	87,2	0,5693	
$\Delta$	50 %	400	50	745	0,667	120	59,71	705	55	92,1	0,7182	
$\Delta$	75 %	400	50	741	1,2	160,8	88,23	1063	82,5	93,5	0,792	
$\Delta$	<b>100 %</b>	<b>400</b>	<b>50</b>	<b>736</b>	<b>1,867</b>	<b>204,5</b>	<b>117,2</b>	<b>1427</b>	<b>110</b>	<b>93,8</b>	<b>0,8276</b>	
$\Delta$	125 %	400	50	730	2,667	254,5	146,9	1799	138	93,6	0,8331	

#### BREAKDOWN TORQUE TEST

Conn.	U [V]	f [Hz]	I [A]	n [min-1]	T <sub>N</sub> [Nm]	P <sub>res</sub> out [kW]	P <sub>ass</sub> , abs [kW]	$\eta$ %	cos $\phi$
$\Delta$	400	50			2850				

#### LOCKED ROTOR TEST

Conn.	U [V]	f [Hz]	T <sub>1</sub> [Nm]	I <sub>lss</sub> , abs. [A]	P <sub>ass</sub> , abs [kW]	cos $\phi$	RATIO		
							I <sub>l</sub> / I <sub>N</sub>	T <sub>1</sub> / T <sub>N</sub>	T <sub>1</sub> / T <sub>N</sub>
$\Delta$	400	50	2560	1346					

#### DIELECTRIC TEST

Between Windings and the Frame

Test N°	U [V]	[a]
	2380	0.02A

#### NO-LOAD TEST

Conn.	U [V]	f [Hz]	n <sub>N</sub> [min-1]	I <sub>lss</sub> , abs. [A]	P <sub>ass</sub> , abs [kW]	cos $\phi$
$\Delta$	400	50	749	90	5000	0,0773

#### LWA [dB(A)]

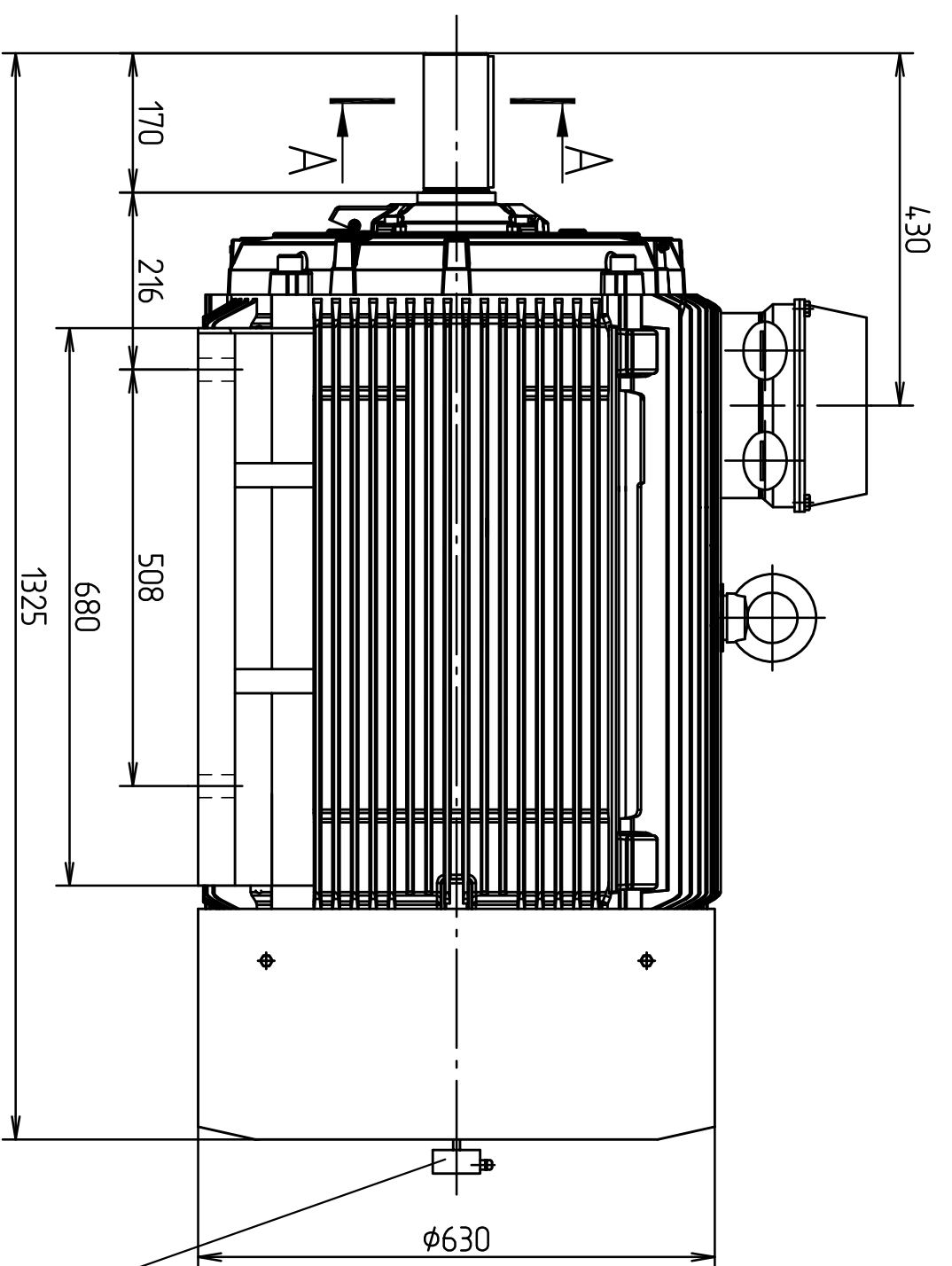
No Load	Load
73	

#### INSUL. RES.

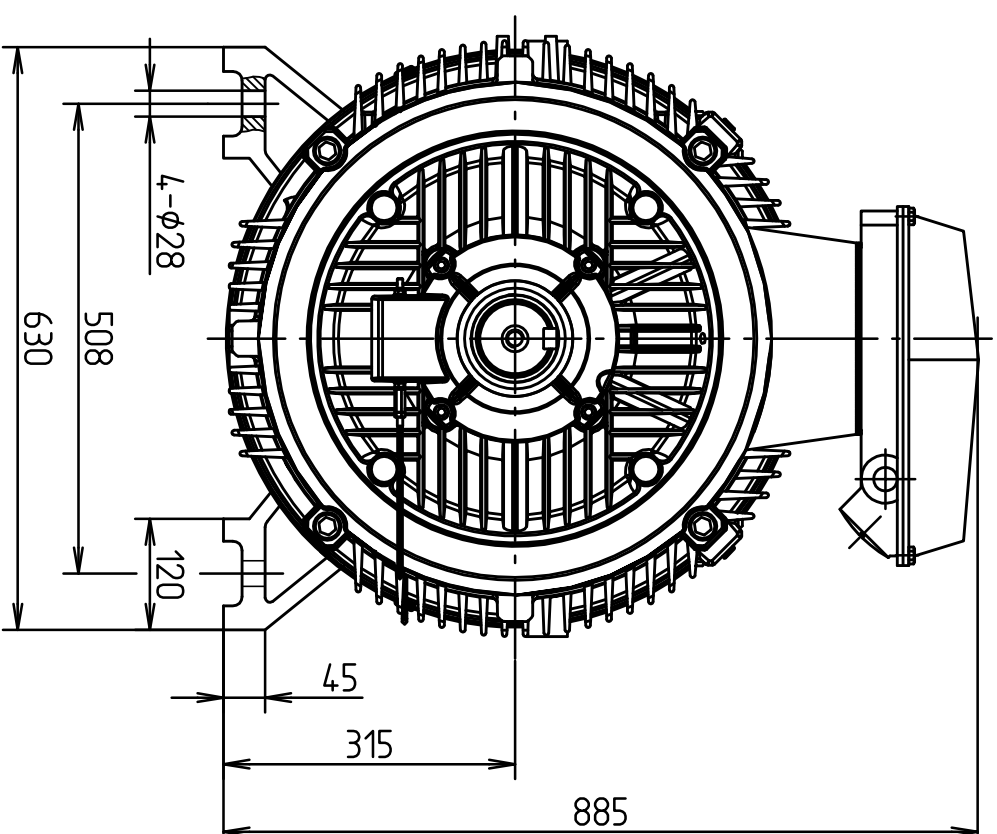
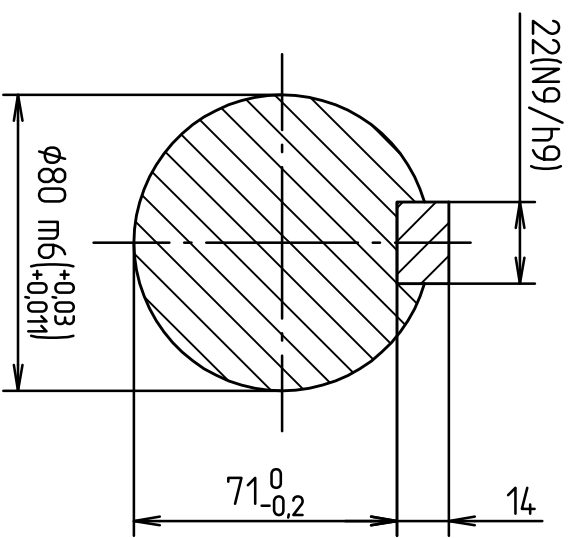
amb. T [°C]	U [V]	[M $\Omega$ ]
19	1000	500

NOTE:

Signature:



A-A



Encoder: H0G 10 DN 1024 I LR 16H7+ESL90

Datum	20.04.2016	Name	E. Babynin
Bearbeiter	20.04.2016	Geprüft	V. Grigan
Geändert	20.04.2016		

**F&OQUET**  
1<sup>st</sup> In Electrical Power Machines

MF 315LB-08

Ref. 2016 0433-A

A3

<b>Data</b>		
<b>Rotor</b>		Squirrel Cage Rotor
<b>Type</b>		<b>MF 355MB-08</b>
<b>Serial Number</b>		20160433-02
<b>Design</b>		IEC 34-1 / EN60034-1
<b>Duty</b>		S1
<b>Phase</b>		3
<b>Power</b>	kW	160
<b>Voltage</b>	V	400
<b>Tolerance</b>	%	+/- 10
<b>Frequency</b>	Hz	50
<b>Tolerance</b>	%	+/- 2
<b>Connection</b>		Δ
<b>Poles</b>		8
<b>Speed</b>	rpm	740
<b>Direction of Rotation</b>		Both
<b>Current</b>	A	299
<b>Efficiency</b>	%	94,2
<b>Power Factor</b>		0,82
<b>Torque</b>	Nm	2.064
<b>Start Up</b>		DOL / VFD
<b>I<sub>A</sub>/I<sub>N</sub></b>	%	640
<b>M<sub>A</sub>/M<sub>N</sub></b>	%	180
<b>M<sub>K</sub>/M<sub>N</sub></b>	%	200
<b>Mounting</b>		IM B3
<b>Frame Size</b>		355 M
<b>Housing material</b>		Cast Iron
<b>Protection</b>		IP 55
<b>Cooling</b>		IC 411
<b>Balancing</b>		Half Key
<b>Insulation class</b>		F
<b>Temperature Rise</b>		B
<b>Weight</b>	kg	~2.200



<b>Bearings &amp; Lubrication</b>		
<b>Bearing Type</b>	Antifriction Bearing	
<b>Cooling</b>	Self Cooled	
<b>Type</b>	Drive End	6322.C3
	Non Drive End	6322.C3 – Insulated
<b>Lubrication interval</b>	h	6.300
<b>Volume of Grease</b>	g	60
<b>Lubricant</b>	Caltex SRI-2	
<b>Painting</b>		
<b>System</b>	Moderate	
<b>Colour</b>	RAL 7030	
<b>Vibration</b>		
<b>Vibration</b>	mm/s	< 2,8
<b>Starting</b>		
<b>Starts</b>	Cold	3
	Warm	2
	Per Year	1.000
<b>Ambiance</b>		
<b>Ambient temperature</b>	°C	- 20 ... + 40
<b>Altitude</b>	m above sea level	≤ 1.270
<b>Humidity</b>	%	< 95
<b>Installation</b>	Outdoor / Indoor	
<b>Accessories</b>		
Regreasing device		
KTY 84/130 Sensor		
Metal Fan		
Encoder Hübner HOG 10 DN 1024 I LR 16H7 + ESL90		

Date (d/m/y): 20/04/2016  
 Customer: TES  
 Motor: MF 355MB-08  
 Serial No: 20160433-02

### Test Report

#### Name-Plate Data

Duty	S1	$\Delta$		
f [Hz]	50	U <sub>N</sub> [V]	400	cos $\phi$ 0,82
n <sub>N</sub> [min-1]	740	I <sub>N</sub> [A]	299	P <sub>N</sub> [kW] 160
IP	55	IS.Class	F	Net B3 [kg] 2150

Drive-end Bearing	6322.C3	Non drive-end Bearing	6322.C3
Phase-Resistance at 20°C	[ $\Omega$ ] 0,0181	[ $\Omega$ ] 0,0182	[ $\Omega$ ] 0,0182

#### TEMPERATURE-RISE TEST

Conn.	U [V]	f [Hz]	I <sub>N</sub> ass I <sub>N</sub> abs [A]	P <sub>N</sub> ress P <sub>N</sub> out [kW]	Lasting [h]	Terminals	Winding $\theta$		Wind. Res. [ $\Omega$ ]	Amb. $\theta$ [°C]	Frame $\theta$		Wind. Res. [ $\Omega$ ]	Temperature Rise $\Delta\theta$ [K]
							Initial				Final			
							[°C]	[°C]			[°C]	[°C]		
$\Delta$	400	50	300	160	4		19	0,018		22	61	0,0233	68,2	

#### LOAD TEST

Conn.	Load	U [V]	f [Hz]	n [min-1]	S %	I [A]	input [kW]	T <sub>N</sub> [Nm]	out [kW]	$\eta$ %	cos $\phi$	Notes
$\Delta$	25 %	400	50	749	0,133	130	45,43	510	40	88,1	0,5044	
$\Delta$	50 %	400	50	747	0,4	180	86,1	1023	80	92,9	0,6905	
$\Delta$	75 %	400	50	744	0,8	234	127	1540	120	94,5	0,7834	
$\Delta$	<b>100 %</b>	<b>400</b>	<b>50</b>	<b>741</b>	<b>1,2</b>	<b>298</b>	<b>168,5</b>	<b>2062</b>	<b>160</b>	<b>95</b>	<b>0,8161</b>	
$\Delta$	125 %	400	50	736	1,867	371	210,5	2595	200	95	0,8189	

#### BREAKDOWN TORQUE TEST

Conn.	U [V]	f [Hz]	I [A]	n [min-1]	T <sub>N</sub> [Nm]	P <sub>ress out</sub> [kW]	P <sub>ass, abs</sub> [kW]	$\eta$ %	cos $\phi$
$\Delta$	400	50			4140				

#### LOCKED ROTOR TEST

Conn.	U [V]	f [Hz]	T <sub>1</sub> [Nm]	I <sub>lss, abs.</sub> [A]	P <sub>ass, abs</sub> [kW]	cos $\phi$	RATIO		
							I <sub>l</sub> / I <sub>N</sub>	T <sub>1</sub> / T <sub>N</sub>	T <sub>1</sub> / T <sub>N</sub>
$\Delta$	400	50	3720	1907					

#### NO-LOAD TEST

Conn.	U [V]	f [Hz]	n <sub>N</sub> [min-1]	I <sub>lss, abs.</sub> [A]	P <sub>ass, abs</sub> [kW]	cos $\phi$
$\Delta$	400	50	749	140	6000	0,0596

LWA [dB(A)]	
No Load	81
Load	

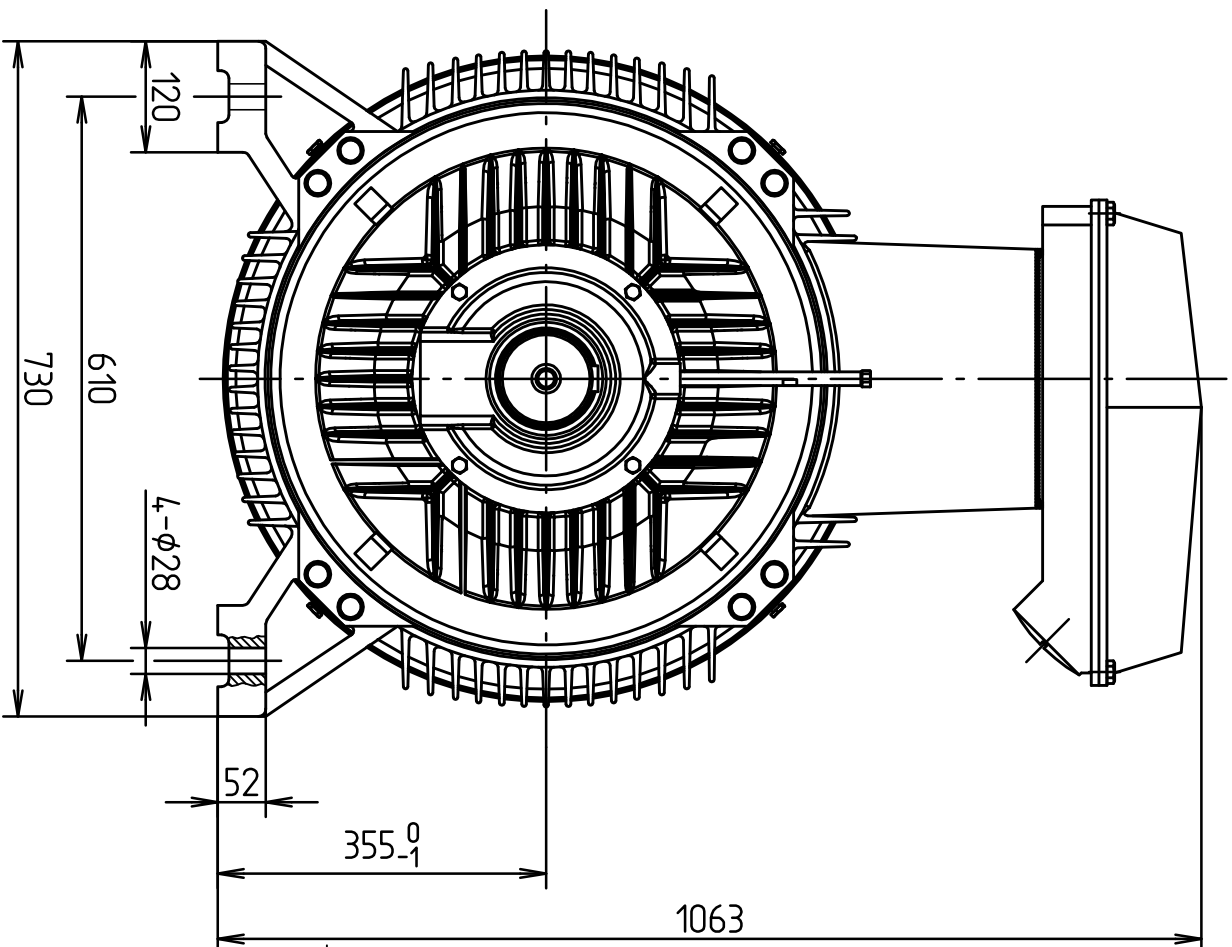
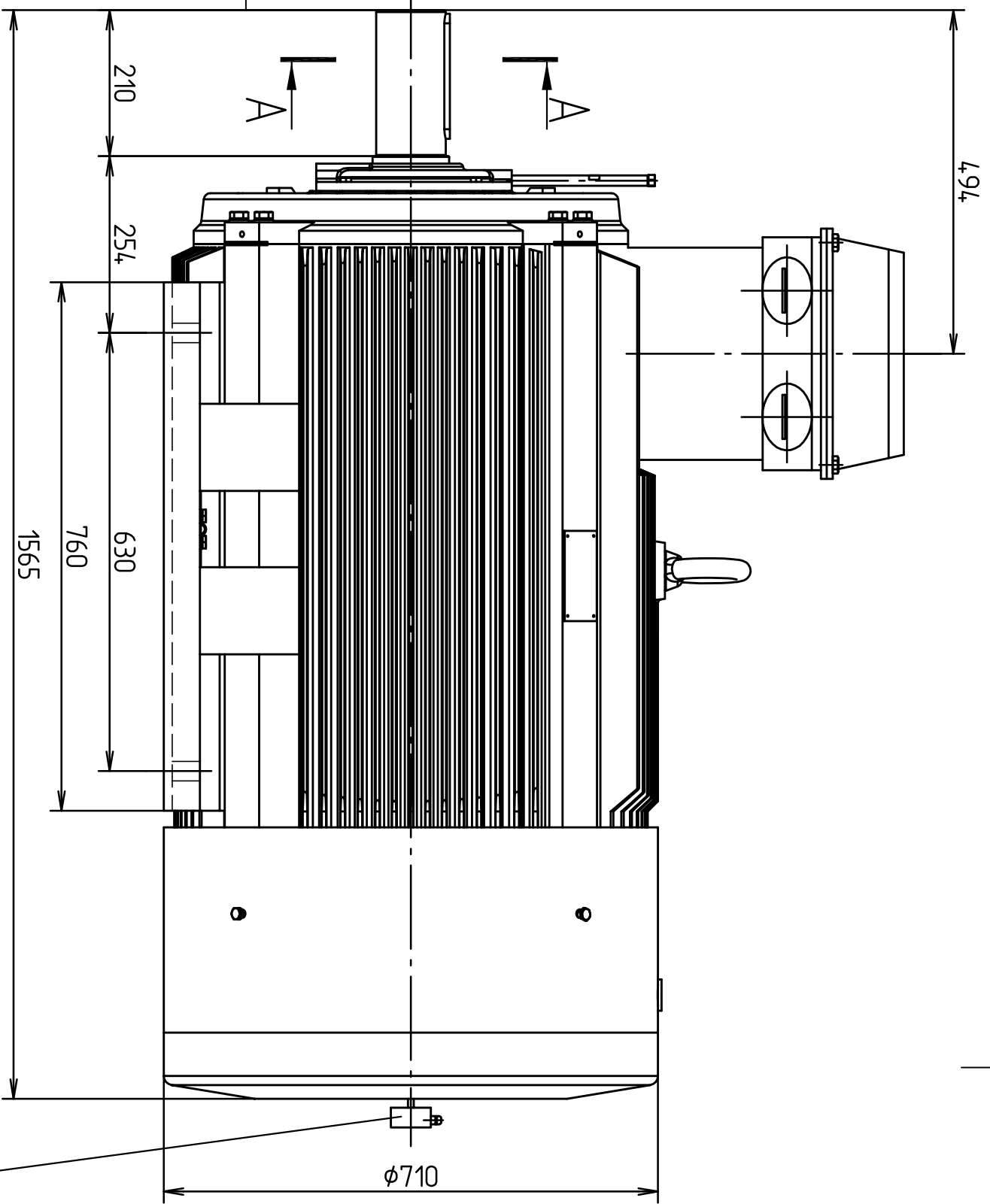
**DIELECTRIC TEST**  
 Between Windings and the Frame

Test N°	U [V]	[a]
	2380	0.02A

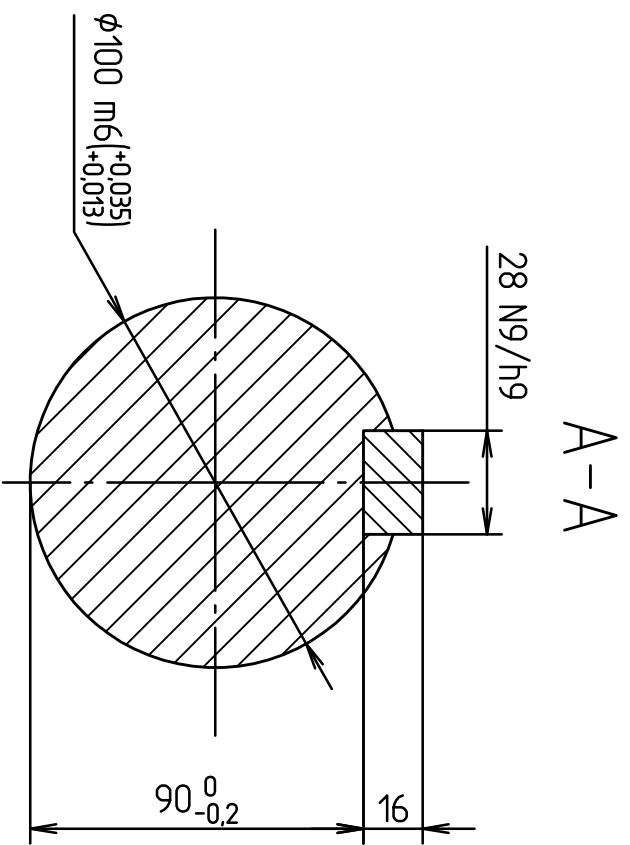
INSUL. RES.		
amb. T [°C]	U [V]	[M $\Omega$ ]
19	1000	500

NOTE:

Signature:



Encoder: H06 10 DN 1024 I LR 16HT+ESL90



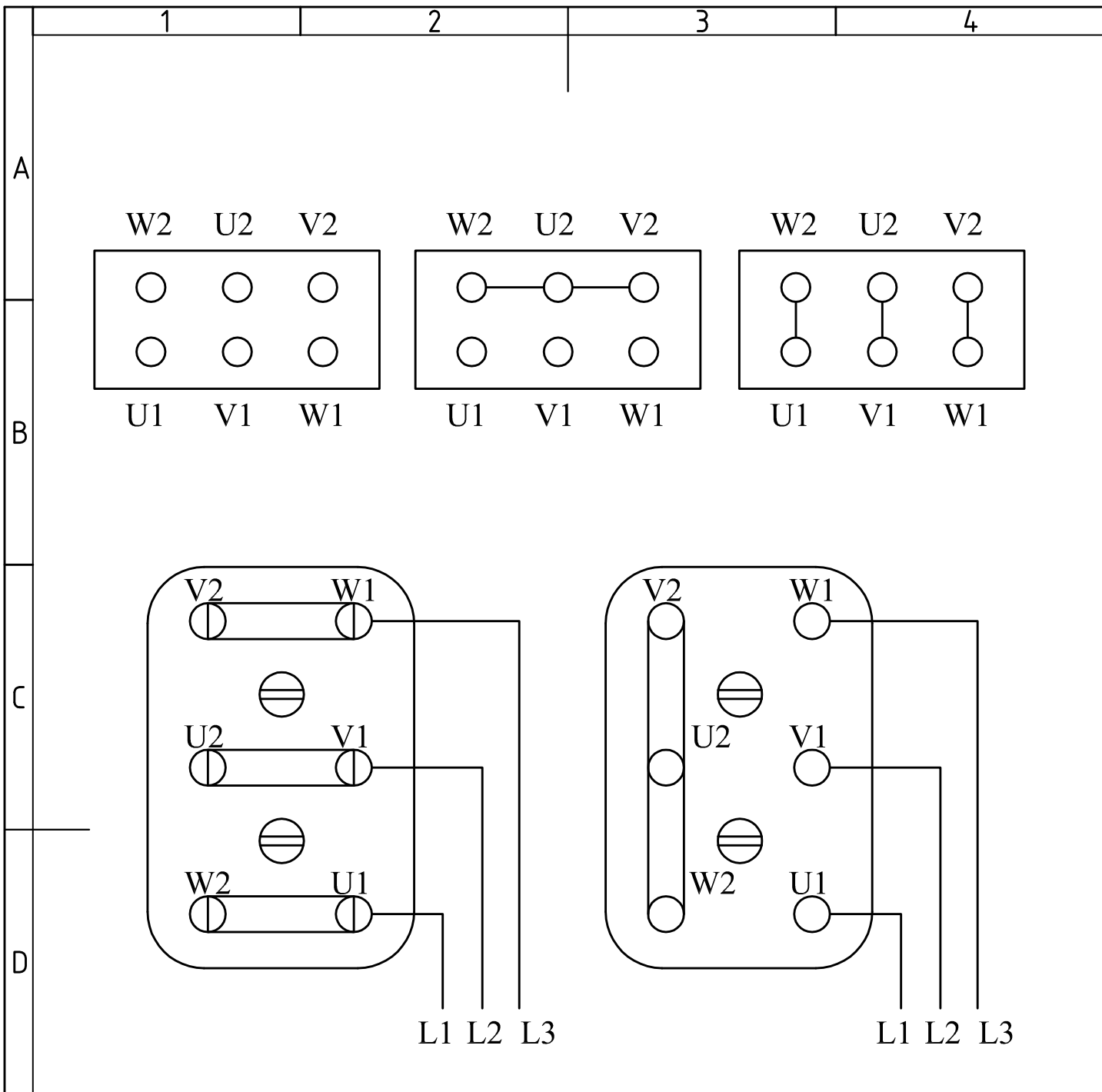
Datum	Name
Bearbeiter 20.04.2016	E. Babynin
Geprüft 20.04.2016	V. Grigan
Geändert	

**F&CQUET**  
1<sup>st</sup> In Electrical Power Machines

MF 355MB-08

Ref. 2016 0433-B

A3



Δ (DELTA)  
CONNECTION

Y (STAR)  
CONNECTION

				Datum	Name
			Bearbeitet	22.12.2015	E. Babynin
			Geprüft	22.12.2015	V. Grigan
			Geändert		



Motor Connection



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